A		Reg. No. :										
		Question Pa	oer Cod	le: 9	670)4						
B.E. / B.Tech. DEGREE EXAMINATION, NOV 2023												
Sixth Semester												
Mechanical Engineering												
	19UME604 - Mechatronics											
		(Regulatio	ons 2019)									
Dura	ation: Three hours	Maximum: 100 Marks										
		Answer ALI	Question	ns								
		PART A - (10 x	1 = 10 M	larks)							
1.	Material Used in K Type Thermocouple are						CO	1- U				
	(a) Chromel/aluminum	(d) Iron / Constantan										
	(c) Chromel/Constanta	(d) Copper / Constantan										
2.	What is the Resolution	/hat is the Resolution of Absolute Encoder, if it has 8 Tracks CO1- U										
	(a) 1.406 Degree	(b) 2.05 Degree	(c) 45]	Degr	ee		(d) 9	0 De	gree			
3.	Which element is us Mechanical Power	ed to converts hy	draulic p	owei	int :	0				CO	1- U	
	(a) Compressor	(b) Pump	(c) Ac	tuato	r		(d) Co	nvert	ors		
4.	is Used to avo excess pressure raise in	Compress	sor d	ue t	0				CO	1- U		
	(a) DC Valve	(b) Pressure Relief Valve										
	(c) Flow Control Valve	e (d) All of the above										
5.	Select the Universal G								CO	1- U		
	(a) NAND and NOR		(b) AND	and	OR							
	(c) NOT and AND		(d) None	of th	ie ab	ove						
6.	Choose the correct decimal Number – 53.	binary Equivalent 625	number	for	the					CO	1- U	
	(a) (110101.1010) ₂	(b) (111101.1010)	(c) (1)	1000	1.10	10)2	(d) (10	010	1.10	10)2	

7.	The	The PLC is used in										
	(a) N	Machine tools	nt									
	(c) n	noulding and extrusion machines	(d) all of the above									
8.	The	acronym PLC stands for:		CO1- U								
	(a) F	Pressure Load Control	(b) Programmable Logic Controll	er								
	(c) F	Pneumatic Logic Capstan	(d) Pressure Loss Chamber									
9.	In t exan	n the level of integration of Mechatronics system, an xample of the first level is										
	(a) F	Fluid valves	(b) Automatic machine tools									
	(c) I	ndustrial robots	(d) Microprocessors									
10.	Which sensor is used in engine management system to measure burned exhaust gas											
	(a) (Dxygen sensor	(b) temperature sensor									
	(a) s	peed sensor	(d) Hall effect sensor									
	PART - B (5 x 2= 10 Marks)											
11.	Explain Inverse Piezoelectric Effect with Examples											
12.	Outline the symbol of SCR Neatly											
13.	Illustrate some properties of Boolean algebra											
14.	Explain ON Delay and OFF delay timer with ladder diagrams											
15.	. Outline the function of Oxygen sensor in Engine Management system											
		PART - C (5 x)	x 16= 80 Marks)									
16.	(a)	Outline briefly about Piezoelectric Sensors	Sensor & Hall Effect CO1-U	(16)								
	(b)	Or Illustrate the building blocks of a indicating various modules involved i Mechatronics System	a Mechatronic System, CO1-U in it & Explain Types of	U (16)								
17.	(a)	Outline the 2/2, 3/2, 4/2, & 4/3 I Construction & Working Neatly Or	Direction Control Valve CO2-U	(16)								
	(b)	Illustrate the Stepper Motor Definitio working of Various types of Stepper M	n Clearly & Explain the CO2-U Motor with Neat Sketch	(16)								

18. (a) Apply the Concept of Basic System Model & Derive the CO3- App (16) Differential Equation for the following Mechanical System



- Or
- (b) Apply the Concept of Basic System Model of Electrical CO3- App (16) system & Do the mess analysis for RL system, RC system, RLC system
- 19. (a) Examine a PLC ladder logic diagram for the application stated CO4- App (16) below.

There are three mixing devices on a processing lines A,B,C after the process begins. Mixer A is to start, after 7 sec is elapsed, next Mixer B is to start, 3.6sec after A. Mixer C is to start 5sec after B all remains ON until a Master enable switch is turned OFF.

Or

(b) Examine a PLC ladder logic diagram for the application stated CO4- App (16) below

A motor and its lubricating pump motor are both running. Lubrication for main motor bearings is required during motor coast down time. After the main motor is shut off the lubricating pump remains ON for a time corresponding to coast down time of 20 sec

20. (a) Design a pick and place robot using mechatronics elements CO6-C (16) and explain the Robot control.

Or

(b) Construct the various stages in designing a mechatronics CO2- App (16) system