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Question Paper Code: U4705

B.E. / B.Tech. DEGREE EXAMINATION, NOV 2023

Fourth Semester

Mechanical Engineering

21UME405- MEASUREMENTS AND INSTRUMENTATION

(Regulations 2021)

Dur	ation: Three hours	Maximum: 100 Marks					
	Answer All Ques	tions					
	PART A - $(10 \times 1 = 1)$	0 Marks)					
1.	The degree of closeness of the measured value of value is known as	a certain quantity with its true	CO1-U				
	(a) Accuracy (b) Precision	(c) Standard (d) Sensitivity					
2.	Systematic errors are		CO1-U				
	(a) Randomly distributed	(b) Regularly repetitive	in nature				
	(c) Distributed on both + ye and - ye sides of mean	value (d) Unknown errors					
3.	3. From which category 'Sigma comparator' belongs?						
	(a) Optical comparator	(b) Mechanical comparator					
	(c) Mechanical-optical comparator	(d) Pneumatic comparator					
4.	What is used to measure the major diameter of an	external thread?	CO1-U				
	(a) Bench micrometer	(b) Thread micrometer					
	(c) One wire method	(d) All of the above					
5.	5. Which of the following is a contact type of automated inspection method?						
	(a) Inspection probe	(b) Laser scanning					
	(c) Electric field	(d) All of the above					
6.	The current generation CT scanner use	_ for scanning	CO1-U				
	(a) pencil beam and stationary detectors	(b) pencil beam and rotating detectors					
	(c) fan beam and detectors	(d) electron beam and detectors					

7.	Whi	Which of the following devices can be used for measuring torque?							
	(a) I	Helical spring	(b) Flat spiral spring	(c) Bellows	(d) Diaph	nragm			
8.	Load	d cells are used fo	r measuring			(CO1-U		
	(a) I	Large weights only	7	(b) Small wei	ights only				
	(c) V	Weights moving ir	high speed	(d) Slowly m	oving weig	ht			
9.	The data acquisition system implies input data collection								
	(a) i	n mixed signal for	m	(b) in analog	form				
	(c) i	n digital form		(d) in the form	n of binary	codes			
10	Amp	Amplified input signal is digitized through							
	(a) A	A/D converters		(b) D/A conv	erters				
	(c) F	Rectifiers		(d) Sigma del	lta modulate	ors			
			$PART - B (5 \times 2 =$	10Marks)					
11	Define the term reliability.								
12	State the principle of interferometry.								
13	What are the benefits of using CMM?								
14	Differentiate between primary and secondary transducers								
15	5 Outline piezoelectric effect								
			$PART - C (5 \times 1)$	6= 80Marks)					
16	(a)	Discuss the di eliminated?	fferent types of errors	and how they	can be	CO1- U	(16)		
	(b)		diagram of generalized stages with examples.	measurement sys	stem and	CO1- U	(16)		
17	(a)	Explain the con linear measurem		Vernier caliper	used for	CO1- U	(16)		
	(h)	Evoloin the	Or king principle of angle D	oldron with a	ot alratal	CO1 II	(16)		
	(b)	•	king principle of angle Doplications of angle Dekko		ii skeich.	COI- U	(16)		

- 18 (a) Explain the working process of Machine vision system, components, CO1 -U (16) application and Benefits.
 - (b) Discuss the need, types and constructional features of coordinate CO1-U (16) measuring machine
- 19 (a) Explain with a neat diagram construction and working an eddy CO1- U (16) current dynamometer

Or

- (b) Explain with a neat diagram construction and working of a prony CO1-U (16) brake for estimating power.
- 20 (a) Describe the different criteria for selection of transducer for a CO1-U (16) particular application.

Or

(b) Describe with the neat block diagram explain single and CO1- U (16) multichannel data acquisition system. Give example for each.