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<b>Question Paper Code: U4301</b>
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B.E./B.Tech. DEGREE EXAMINATION, NOV 2023

Fourth Semester

Electrical and Electronics Engineering

21UEE401- ELECTRICAL MACHINES II

(Regulations 2021)

Duration: Three hours

Maximum: 100 Marks

## PART A - (10 x 1 = 10 Marks)

1.	What is the highest possible speed by turbo alternators?			CO1-U
	(a) 3000 rpm	(b) 1500 rpm	(c) 1000 rpm	(d) 4000 rpm
2.	What kind of rotor is most suitable for turbo alternators?			CO1-U
	(a) Salient pole type	(b) Non-salient pole type	(c) both type	(d) none of the above
3.	Slip ring induction motor has			CO2-U
	(a) Low starting torque		(b) Medium starting torque	
	(c) High starting torque		(d) None of these	
4.	What is the condition for maximum torque			CO2-U
	(a) $R_2 = X_2$	(b) $R_2 = sX_2$	(c) $R_2 = 1/X_2$	(d) $R_2 = X_2^2$
5.	Which type of starter is used in Pumps and Compressors			CO3-U
	(a) DOL Starter		(b) Star Delta Starter	
	(c) Auto Transformer Starter		(d) All the above	
6.	Static Kramer Slip power Recovery scheme is used for			CO3-U
	(a) Sub Synchronous Speed control		(b) Super Synchronous Speed control	
	(c) Sub and Super Synchronous Speed Control		(d) None of these	
7.	The developed torque of a synchronous motor varies as			CO4-U
	(a) Applied voltage V			
	(b) Inversely proposed to applied voltage			
	(c) Directly proposed to square of applied voltage			

	(d) Inversely proposed to square of applied voltage			
8.	In a synchronous motor, torque or load angle ----- with increase in load			CO4-U
	(a) Increases	(b) Decreases	(c) Remains unaffected	(d) None of the above
9.	In a single phase induction motor, the starting torque developed is proportional to			CO5-U
	(a) Square of V	(b) 1/(Square of V)	(c) 1/V	(d) V
10.	Single phase motors are commercially manufactured up to			CO5-U
	(a) 2HP	(c) 5HP	(c) 10HP	(d) 15HP
PART – B (5 x 2= 10Marks)				
11.	Why salient pole construction is not used for high speed Alternators			CO1-U
12.	Explain crawling in three phase Induction motor			CO2-U
13.	State various methods of starting 3 phase Induction motor			CO3-U
14.	List the starting methods of Synchronous motor.			CO4-U
15.	What is meant by Step angle in Stepper motor?			CO5-U
PART – C (5 x 16= 80Marks)				
16.	(a)	Explain the emf and mmf methods of determining the voltage regulation of an alternator.		CO1-App (16)
		Or		
	(b)	Explain the ZPF (Portier) method of determining the regulation of an alternator.		CO1-App (16)
17.	(a)	Draw and Explain Slip Torque characteristics of induction motor with the effect of changing Rotor resistance.		CO2-App (16)
		Or		
	(b)	Explain the Equivalent circuit of Induction motor		CO2-Ana (16)
18.	(a)	Explain in detail about the slip power recovery scheme.		CO3-Ana (16)
		Or		
	(b)	Explain the speed control of a three phase induction motor using voltage control and frequency control.		CO3-Ana (16)
19.	(a)	Draw and Explain V-curves and inverted V-curves..		CO4-U (16)
		Or		
	(b)	Discuss the various starting methods of a synchronous motor.		CO4-U (16)

20.	(a)	Explain the operating principle of Linear Induction Motor with neat diagram. Mention its Applications	CO5-U	(16)
		Or		
	(b)	Explain the construction and working principle of stepper motor. Mention its Applications	CO5-U	(16)