Reg. No. :

Question Paper Code: 99304

B.E. / B.Tech. DEGREE EXAMINATION, NOV 2023

Elective

Electrical and Electronics Engineering

19UEE904 - SPECIAL ELECTRICAL MACHINES

(Regulations 2019)

Duration: Three hours

Maximum: 100 Marks

Answer ALL Questions

PART A - (10 x 1 = 10 Marks)

1.	In PMBLDC motor Field Magnet on the					
	(a) Stator	(b) Rotor	(c) both (a) and b)	(d) None of the above		
2.	The speed of perman	ent magnet BLDC moto	or cannot be controlled l	oy CO1- U		
	(a) Rheostatic contro	ol method	(b) Flux control me	ethod		
	(c) Electronic circuits		(d) None of the abo	ove		
3.	Pmsm working principle is					
	(a) Amphere circuita	l law (b) ohms law	(c) magnetic locking	(d) lenz law		
4.	EMF equation of the	PMSM similar to		CO2-U		
	(a) Transformer	(b)dc machine	(c) stepper motor	(d) None of the above		
5.	What is the angle be	tween stator direct axis	and quadrature axis?	CO3-R		
	(a) 90°	(b)0°	(c) 45°	(d) 60°		
6.	Types of control tech	nniques used in SRM		CO3- R		
	(a) Voltage control	(b)Frequency contro	ol (c)v/f control	(d) Hysteresis control		
7.	Operation of stepper	motor at high speed is 1	referred to as	CO4- U		
	(a) Fast forward (b	o)Slewing	(c)Inching	(d) Jogging		
8.	Torque constant of a stepper motor is also called as					
	(a) Détente torque	(b)Torque sensitivity	(c)Pull in torque	(d) Pull out torque		

9.	Radial airgap motor has					05- R					
	(a) a	a) axial laminations (b)radial laminations (c)both laminations (d) no				one of the above					
10.	A li	near Induction Motor may be			С	O5- R					
	(a) S	(a) Single sided / Double sided (b)Primary / secondary									
	(c)n	one of the above	(d) both a &b								
PART - B (5 x 2= 10 Marks)											
11.	List out the different classifications of BLPM DC motor CO1-U										
12.	What are the assumptions made in the derivation of EMF equation for PMSM? CO2										
13.	Illustrate the different modes of operation of switched reluctance motor.										
14.	Define step angle.										
15.	List the applications of synchronous reluctance motors.				CO5 -U						
PART – C (5 x 16= 80 Marks)											
16.	(a)	Explain the Construction & principle of opera	tion of PMBLDC mot	or.	CO1- U	(16)					
Or											
	 (b) Sketch the structure of power controller for PMBLDC motor & Explain the functions of each block 				CO1- U	(16)					
17.	(a)	(a) Draw and explain the phasor diagram of PMSM Or			CO2- U	(16)					
	(b)	Discuss about various power controller used	in PMSM motor		CO2- Ana	(16)					
18.	(a)	Draw the cross sectional view of switch explain the principle of Operation	ned reluctance motor	and	CO3- Ana	(16)					
	(b)	Describe the following: (i) Role of microprocessors in control of swi (ii) Sensorless operation	itched reluctance moto	or	CO3- U	(16)					
19.	(a)	Describe in detail the construction and work stepper motor.	king of variable reluct	ance	CO4- R	(16)					
(h) Drow and availain drive aircryite and their nonfermance elementaristics (204 H (10)											
	(D)	for stepper motor	errormance character	ISTICS	UU4- U	(16)					

20. (a) Describe the constructional features and operation of variable CO5-U (16) reluctance synchronous reluctance motor

Or

(b) Describe briefly about the repulsion motor. CO5- R (16)