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Question Paper Code: U9376

B.E. / B.Tech. DEGREE EXAMINATION, NOV 2025

Open Elective

21UEE976 – INDUSTRIAL AUTOMATION AND CONTROL

(Regulations 2021)

(Common to ALL Engineering Branches)

Duration: Three hours

Maximum: 100 Marks

Answer ALL Questions

PART A - (10 x 1 = 10 Marks)

- Using the state of an output device as input in the further stages of ladder logic program is called as _____. CO1-U
a) Feedback b) Latching c) Breaking d) Swapping
- The interface with sensors to collect telemetry data and forward it to a primary system for further action in SCADA is called as _____. CO1-U
a) HMI b) RTU c) Field device d) Production control
- Resistive Temperature Detectors (RTD) have _____. CO1-U
a) positive temperature coefficient b) negative temperature coefficient
c) Zero temperature coefficient d) None of these
- The mechanical device that uses a power source to operate a valve is called as _____. CO1-U
a) Valve b) Actuator
c) Controller d) None of these
- HMI stands for _____. CO1-U
a) Hybrid Machine Interface b) Human Machine Interface
c) Higher Machine Interface d) Human Machine Interference
- Which of the following is not the component of HMI? CO1-U
a) Control Panel b) Recorder c) Display unit d) All of the above

7. The inputs and outputs in a PLC system are _____. CO1-U
- a) Sensors and actuators b) Motors and gears
c) Valves and pumps d) Programs and data
8. PLC handle multiple inputs and outputs using _____. CO1-U
- a) a single input/output (I/O) module
b) a multiple input/output (I/O) module
c) a single input multi-output module
d) Multiple inputs and single output module
9. Which of the following is a benefit of using a modular architecture in DCS hardware? CO1-U
- a) Reduced scalability b) Limited flexibility
c) Ease of maintenance d) Higher cost
10. What is the purpose of loop checking in DCS programming? CO1-U
- a) To test the performance of the control loops
b) To verify the integrity of field device connections
c) To optimize control strategy parameters
d) To synchronize clocks across devices

PART – B (5 x 2= 10 Marks)

11. Contrast relay logic and programmable logic by highlighting their features and use cases. CO1-U
12. Discuss the basic elements of computer-aided measurement and control and associate them with their respective roles. CO1-U
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14. List and describe any two output devices used with a PLC and discuss their applications. CO1-U
15. Describe common applications of DCS in industrial environments. CO1-U

PART – C (5 x 16= 80 Marks)

16. (a) Examine the features and structure of PROFIBUS used in CO4–App (16) industrial automation with the help of a diagram.

Or

- (b) Demonstrate the key features and architecture of MODBUS protocol with a suitable diagram and show its application in automation systems. CO4-App (16)
17. (a) Explain the working principle of servo drives and discuss their role and importance in industrial automation. CO1-U (16)
- Or
- (b) Write detailed notes on DIAC and TRIAC, explain their function in industrial automation systems, and compare their characteristics. CO1-U (16)
18. (a) Draw and illustrate the hierarchical levels in an industrial communication network, and demonstrate the function of each level. CO3-App (16)
- Or
- (b) List four basic types of messages sent by field devices in a computer-based measurement and control system and demonstrate their significance. CO3-App (16)
19. (a) Draw a Sequential Flow/Function Chart for a simple PLC-controlled process and demonstrate its significance in ladder logic development. CO2-App (16)
- Or
- (b) Use your understanding of PLC systems to list and explain the communication protocols suitable for PLC communication. CO4-App (16)
20. (a) Break down the salient features of DCS and analyze their impact on system flexibility, scalability, and performance in complex process industries. CO6-Ana (16)
- Or
- (b) Analyze the integration of DCS with other automation systems such as PLCs and SCADA, and classify the advantages based on system architecture and process complexity. CO6-Ana (16)

