		Question Paper : U5104		
M.E. DEGREE EXAMINATION, NOV 2024				
Professional Elective				
CAD / CAM				
21PCD505-INDUSTRIAL ROBOTICS AND EXPERT SYSTEMS				
(Regulations 2021)				
Duration: Three hours Maxin			num: 100 Marks	
Answer ALL Questions				
PART - A $(5 \times 20 = 100 \text{ Marks})$				
1.	(a)	How do the anatomical design features of robots influence their precision movement capabilities, and what role do various sensors play in enhancing this precision in robotic systems? Or	CO1- U	(20)
	(b)	How can the principles of robot kinematics be applied to improve the control of robotic manipulators, and what challenges arise in achieving accurate motion and positioning during complex tasks?	CO1- U	(20)
2.	(a)	Develop a design for an electro-hydraulic servo valve system that enhances the responsiveness and accuracy of a robotic manipulator in a manufacturing setting. Or	CO3- App	(20)
	(b)	How do the design characteristics of vacuum, magnetic, and air- operated grippers influence their effectiveness as end effectors in robotic systems, and what factors should be considered when selecting an appropriate gripper for specific industrial applications?	CO3- App	(20)
3.	(a)	Choose the most suitable proximity and range sensor for a robot tasked with identifying objects in a cluttered environment, and explain the advantages of your selection. Or	CO3- App	(20)
	(b)	Identify the best method for determining the orientation of an object in robotic pick-and-place operations, and explain how it impacts the robot's performance.	CO3- App	(20)

Reg. No.:

4. (a) What are the key technological advancements in mining robotics, CO4- App (20) and how do these innovations improve efficiency, sustainability, and productivity in modern farming practices?

Or

- (b) Develop a safety protocol for robotic operations in a nuclear CO4-App (20) facility, addressing the specific risks associated with radiation and hazardous materials.
- 5. (a) Identify key characteristics of textual robot programming CO5-App (20) languages and explain how they can be utilized to optimize robot motion control in a pick-and-place operation.

Or

(b) How can you analyze the impact of artificial intelligence CO5-App (20) applications in robotics on the autonomy and decision-making capabilities of robotic systems, and in what ways can these enhancements lead to increased efficiency in specific industries?