		Reg. No. :													
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Question Paper Code:U5104															
M.E. DEGREE EXAMINATION, NOV2024															
Professional Elective															
CAD / CAM															
21PCD504-MECHATRONCIS IN MANUFACTURING SYSTEM															
	(Regulations 2021)														
atior	: Three hours								Max	kimu	m: 1	00 M	arks		
		Answe	er AL	$L Q_1$	uesti	ons	1)								
(a)	Explain in detail t Mechatronics.	the role and	(5 x ) fund	zo = ction	of	con	ks) trol	syste	ems	in	CO1	- U	(2	20)	
		(	Dr												
(b)	Discuss in detail the different types of measurement systems CO1- U (2 utilized in robotic applications.										20)				
(a)	In which applications are light sensors commonly used? Explain your answer, detailing the working principles of light sensors in these applications.									in in	CO2	- Ap	(2	20)	
		(	Dr												
(b)	Discuss the types of flow levels. Explain sketches.	f sensors use n their work	ed for ting	r me prin	easur: ciple	ing t s an	emp d p	eratı rovic	ire a le no	nd eat	CO2	- Ap	(2	20)	
(a)	Identify and recomposition of the microprocessor a	mend a suital your choice as architecture.	ole m nd co	nicro onclu	proc ide v	essor vith	r for a ne	ap atsk	erson etch	nal of	CO4	- An	(2	20)	
(b)	What components we control system? Su their functionality.	vould you su pport your a	ggest	t for r wi	desi th ex	gnin xamp	g a oles	traff to il	ic lig lustra	ght ate	CO4	- An	(2	20)	

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 4. (a) Outline a methodology for selecting a Programmable Logic CO5- An (20) Controller (PLC) for a specific application, explain in detail the key criteria and considerations involved in the selection process.

Or

- (b) Describe the main components of a Programmable Logic Controller CO5- An (20) (PLC) using a block diagram for a specific application, and provide a short note on jump control in PLCs, including an explanation with a ladder diagram
- 5. (a) Explain the application of mechatronics in Anti-lock Braking CO1-U (20) Systems (ABS), emphasizing its key components, operational principles, and benefits.

Or

(b) How can mechanical systems be effectively modeled using CO1- U (20) mechatronics principles?