С		Reg. No. :												
	Question Paper Code: 99404													
	B.E. / B.Tech. DEGREE EXAMINATION, NOV 2024													
	Elective													
	Electronics and Communication Engineering													
19UEC904- Control Engineering														
(Regulation 2019)														
Dura	Puration: Three hours Maximum: 100 Marks											ζS		
Answer ALL Questions														
PART A - $(5 \times 1 = 5 \text{ Marks})$														
1.	A control system in which the control action is somehow dependent on the CO1-U output is known as											CO1-U		
	(a) Closed loop system (b) Open loop system													
	(c) Semi closed loop system (d) None the above													
2.	The type 0 system has at the origin										(	CO1- U		
	a) no pole (b) net pole (c) simple pole (d) none of the above									e				
3.	By equating the denominator of transfer function to zero, which among the CO1- U following will be obtained?													
	(a) Poles	(a) Poles (b) Zeros (c) Both a and (d) None of the above												
4.	Technique gives quick transient and stability response									(	CO1- U			
	(a) Root locus (b) Bode				(c) Nyquist						(d) Nichols			
5.	State space analysis is applicable even if the initial conditions are								(	CO5- U				
	a) Zero (b) Non-zero (c)) Equal						(d) Not equal							
PART - B (5 x 3 = 15 Marks)														
6.	State Mason's gain formula.										CO1 U			
7.	Determine the Dampi loop transfer function $G(s) = \frac{400}{s^2 + 2s + 400}$	ng ratio and natural ction of a sec	freq	juenc ord	cy of ler	f osc syst	illati tem	on foois	or th gi	ie clo ven	osed by	C	O2 App	

- 8. What are the advantages of Bode plot?
- 9. What is the necessity of compensators?
- 10. Explain the concept of Controllability.

$$PART - C (5 \times 16 = 80 \text{ Marks})$$

11. (a) Using signal flow graph, analyze the overall Transfer function for the CO2-App (16) system shown in the fig.



(b) Demonstrate the differential Equations governing the mechanical CO2-App (16) system shown in the fig. and determine the transfer function.



12. (a) The open loop transfer function of a unity feedback system is given CO3- Ana (16) byG(s)=K/s(Ts+ 1) where K and T are positive constants. By what factor should the amplifier gain be reduced so that the peak overshoot of unit step response of the system is reduced from 75% to 25.

Or

(b) A unity feedback control system has an open loop transfer function CO3- Ana (16) G(S) = 10/s(s+2). Find the rise time, percentage over shoot, peak time and settling time.

CO1 U

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CO1 U

**CO3 U** 

13. (a) The open loop transfer function of a unity feedback system is given by CO3- Ana (16)

$$G(s) = \frac{K}{s(1+0.2s)(1+0.05s)}$$

Sketch the polar plot and determine the value of K such that

(i) gain margin is 18db (ii) phase margin is 60o

Or

(b) Consider a unity feedback system having an open loop transfer CO3- Ana (16) function  $G(s) = \frac{K}{s(s+0.5s)(1+4s)}$ 

Outline the polar plot and determine the value of K so that

- (i) Gain margin is 20db
- (ii) Phase margin is 30°.
- 14. (a) The open loop transfer function of a unity feedback system given by CO3- Ana (16)

 $G(s) = \frac{K(s+9)}{s(s^2+4s+11)}$ . Sketch the root locus of the system and the

evaluate the system stability with respect to their location of poles.

Or

- (b) Using Routh Hurwitz criterion determine the stability of a system CO3- Ana (16) representing the characteristic equation  $s^{6}+2s^{5}+8s^{4}+12s^{3}+20s^{2}+16s+16=0$  and comment on location of the roots of the characteristic equation.
- 15. (a) The State model matrices of a system are given below CO3- Ana (16)

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & -2 & -3 \end{bmatrix}; B = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \text{ and } C = \begin{bmatrix} 3 & 4 & 1 \end{bmatrix}$$

Generalize the Observability of the system using Gilberts test and thereby analyze the stability of the system.

Or

(b) Determine the state variable representation of the system whose

transfer function is given as  $\frac{Y(s)}{U(s)} = \frac{2s^2 + 8s + 7}{(s+2)^2(s+1)}$