			R	eg. No. :									
			Question	Paper	Code: 9	9B17]						
B.E./B.Tech. DEGREE EXAMINATION, NOV 2022													
				Elect	ive								
			Bio	omedical E	Ingineerin	ıg							
		19UBM917-	REHABILIT	TATION E	NGINEE	RING A	ND R	ово	TICS	5			
				(Regulatio	ns 2019)								
Duration: Three hours Maximum									n: 10	100 Marks			
			А	nswer All	Questions	5							
			PAR	ГА - (10х	2 = 20 M	arks)							
1.	Define myoelectric arm.							CO1- U					
2.	Write a short notes on rehabilitation of the visual system.						CO1- U						
3.	Define postural support device.							CO1- U					
4.	Write short notes on truncal and cervical orthoses.							CO1- U					
5.	Mention the advantages and disadvantages of manual wheelchairs.							CO1- U					
6.	Define the principles of coordination exercises.							CO1- U					
7.	"The automation system needs sensors" – justify. CO3- A						Ana						
8.	Is there any way to implement robotics in medicine? Explain your answer.						CO3- Ana						
9.	Is there a need of controller in rehabilitation? Justify.						CO3- Ana						
10.	How is robot different from human?						CO2- App						
			PA	RT - B (5	x 16= 80	Marks)							
11.	(a)	Define is rehab	ilitation engin cepts in senso	neering? E ry and mot	laborate tor rehabi	in detail litation.	abou	t the	CO)1- U	ſ	(16)	
	(b)	Enlighten in deta	ail about the c	onceptual	framewor	rks.			CC	01- U	ſ	(16)	
12.	(a)	Design an intell	igent prosthe	tic knee wi Or	th necess	ary expla	anatio	1.	CC)2- A	pp	(16)	
	(b)	Summarize on thores.	ne constructio	n and worl	king of an	ankle fo	oot		CO	02- A	pp	(16)	

13.	(a)	Describe the design process of a wheel chair. Compare between a manual and a powered wheelchair.	CO3-Ana	(16)
		Or		
	(b)	Design a powered wheel chair system and discuss about the components used.	CO3-Ana	(16)
14.	(a)	Outline the concepts and principles of robotics. Or	CO1- U	(16)
	(b)	Explain the overview of robot subsystems.	CO1- U	(16)
15.	(a)	Write in detail about the fundamentals of robot technology. Or	CO1- U	(16)
	(b)	Describe in detail about the functions of rehabilitation robotics.	CO1- U	(16)