A
$\mathbf{A}$
1 B

Reg. No.:					

# **Question Paper Code: 95704**

## B.E./B.Tech. DEGREE EXAMINATION, DEC 2021

#### Fifth Semester

### Mechanical Engineering

#### 19UME504– MEASURMENTS AND INSTRUMENTATION

	1) CIVIES	or mensormer.	TO THIS HISTROMETIT	1111011		
		(Regula	ation 2019)			
Dura	tion: Three hours			Maximum: 100 M	1arks	
		Answer A	LL Questions			
		PART A - (10	$0 \times 1 = 10 \text{ Marks}$			
1.	. The ease with which observations can be made accurately is referred to as					
	(a) readability	(b) sensitivity	(c) accuracy	(d) precisi	ion	
2.	2. The maximum amount by which the result differs from the true value is called					
	(a) Correction	(b) discrepancy (c) error (d) all of the			above	
3.	Optical flats are made of					
	(a) Quartz	(b) glass	(c) plastic	(d) steel		
4.	The two slip gauges in precision measurement are joined by				CO2- R	
	(a) assembling	(b) sliding	(c) adhesion	(d) wringing		
5.	5. What is the first and the foremost step in image processing					
	(a) Image restoration		(b) Image enhancement			
	(c) Image acquisition	1	(d) Segmentation			
6.	Which of the following is the most important element for stabilizing machine vision inspections in almost all applications?					
	(a) Processing speed	(b) Illumination	(c) High-resolution	(d) Above all		

7.	Piezoelectric load cell are used for measurement in-motion weigh bridges and the principle employed is					
	(a) conversion of pressure into change of resistance					
	(b) conversion of pressure into generation of electrical signal					
	(c) conversion of pressure into change of inductance					
	(d) conversion of pressure into change of capacitance					
8.	A force can be measured by help of	CO5- R				
	(a) Force meter (b) spring balance (c) both a and b (d) pane balance					
9.	Which of the following cannot be considered as data in Data Acquisition System (DAQ)?	CO1- R				
	(a) Temperature (b) Mechanical displacement					
	(c) Flow rate (d) None of the above					
10	Which one is not the type of proximity sensors	CO1- R				
	(a) Eddy current sensor (b) Inductive sensor					
	(c) Hall effect sensor (d) Capacitive sensor					
	$PART - B (5 \times 2 = 10 \text{ Marks})$					
11	Define sensitivity	CO1- U				
12	What are the advantages of pneumatic comparator?.	CO2- U				
13	What is coordinate measuring machine?					
14	Why flow measurement is important?					
15	What is mean by tactile sensor?					
	PART – C (5 x 16= 80 Marks)					
16	(a) Explain the various systematic and random errors in measurements CO1-U	(16)				
	Or (b) Explain Generalized measuring system with neat sketch. CO1-U	(16)				
17	(a) With neat sketch explain the construction and working principle CO2-U of differential pneumatic comparator  Or	(16)				
	(b) With neat diagram explain the construction and working principle CO2-U of depth micrometer?	(16)				

18	(a)	List and explain the various types of CMM	CO3-U	(16)				
		Or						
	(b)	How is CMM used for measuring distance between holes?	CO3-U	(16)				
19.	(a)	Discuss with neat diagram on using a proving ring to measure force.	CO4-U	(16)				
	Or							
	(b)	Explain the construction and working of an orifice meter	CO4-U	(16)				
20.	(a)	Explain the Sensors for Displacement and Position Or	CO5-U	(16)				
	(b)	Write the construction and working principle of engine management system	CO5-U	(16)				