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Reg. No.:					

## **Question Paper Code: 59404**

## B.E. / B.Tech. DEGREE EXAMINATION, MAY 2024

## Elective

## Electronics and Communication Engineering

	Ele	ctronics and Communic	ation Engineering				
15UEC904-LINEAR CONTROL ENGINEERING							
	(Regulation 2015)						
Dura	ation: Three hours	Answer ALL Q		Maximum: 100 Marks			
		PART A - (10 x 1 =	= 10 Marks)				
1.	Which among the follow system?	CO1- R					
	<ul><li>(a) Automatic washing r</li><li>(c) Bread toaster</li></ul>	machine	<ul><li>(b) Automatic electric</li><li>(d) Electric hand dr</li></ul>				
2.	A closed loop system is of the following?	distinguished from open	n loop system by which	ch CO1- R			
	(a) Servomechanism	(b) Feedback	(c) Output patte	ern (d) Input pattern			
3.	By which of the following	ng the system response	can be tested better?	CO2- R			
	(a) Ramp input signal		(b) Sinusoidal input	signal			
	(c) Unit impulse input si	gnal	(d) Exponentially de	ecaying signal			
4.	Which controller has the of offset in proportional	•	overcome the drawbac	ck CO2- R			
	(a) P-I	(b) P-D	(c) Both a and b	(d) None of the above			
5.	Which unit is adopted for	or magnitude measurem	ent in Bode plots?	CO3- R			
	(a) Degree	(b) Decimal	(c) Decibel	(d) Deviation			
6.	The magnitude & phase steady state output is cal	•	•	e CO3- R			
	(a) Step	(b) Ramp	(c) Sinusoidal	(d) Parabolic			

7. Root locus specifies the movement of closed loop poles especially when the gain of system \_\_\_\_\_

CO4-R

(a) Remains constant

(b) Exhibit variations

(c) Gives zero feedback

- (d) Gives infinite poles
- 8. In Routh array, if zero is found in the first column, then by which term it needs to be replaced?

CO4- R

(a)  $\delta$ 

(b) n

- (c) o
- (d) ε
- 9. Which among the following plays a crucial role in determining the state of dynamic system?

CO5- R

- (a) State variables
- (b) State vector
- (c) State space
- (d) State scalar
- 10. State space analysis is applicable even if the initial conditions are \_\_\_\_\_

CO5- R

(a) Zero

- (b) Non-zero
- (c) Equal
- (d) Not equal

$$PART - B$$
 (5 x 2= 10 Marks)

11. State Mason's gain formula.

- CO1- R
- 12. What will be the response of a first order system with unit step input?
- CO2- R

13. What are the characteristics of phase lead network?

CO3-R

14. What is dominant pole?

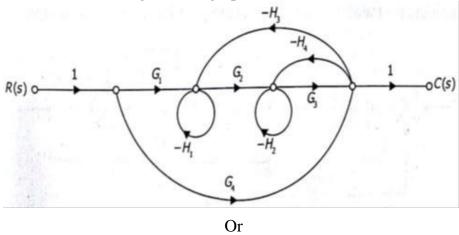
CO4-R

15. Define the state and state variable of a model.

CO5- R

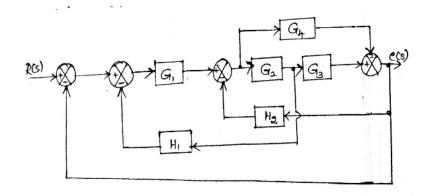
16. (a) Solve C/R for the signal flow graph shown below

CO1 App (16)



(b) How could you determine the Transfer Function of the system Shown in the figure below?

CO1 App (16)



17. (a) Draw the block diagram of second order system. Classify it. CO2-App (16)

Derive the time response of any one of the damped systems for unit step input.

Or

- (b) The open loop transfer function of a unity feedback system is CO2- App given by G(S) = 20/S(S+2). The input function is  $r(t) = 2 + 3t + t^2$ . Examine the generalized errorcoefficient and steady state error.
- 18. (a) Given  $G(S) = ke^{-0.2S}/S(S+2)(S+8)$  CO3- App (16) Draw the Bode plot and find K for the following two cases when (i) Gain margin equal to 6db
  - (ii) Phase margin equal to 45°.

Or

- (b) The open loop transfer function of a unity feedback system is CO3-App (16) given by  $G(S) = 1 / S^2$  (1+S) (1+2S). Sketch the polar plot and determine the gain and phase margin.
- 19. (a) Define Stability. With an example, explain the steps to be CO4-App (16) followed for Routh-Hurwitz criterion.

Or

(b) The open loop transfer function of a unity feedback system is CO4-App (16) given by  $(S) = (S+9)/S(S^2+4S+11)$ . Sketch the root locus of the system and the evaluate the system stability with respect to their location of poles.

20. (a) A system is represented by State equation

CO5- App (16)

 $\dot{X} = Ax + Bu$  and output equation

Y=Cx + Du Where

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -6 & -11 & -6 \end{bmatrix}; \qquad B = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}; \qquad C = \begin{bmatrix} 10 & 5 & 1 \end{bmatrix}$$

Verify the controllability and observability of the control system.

Or

- (b) Determine the state variable representation of the system whose CO5-App (16) transfer function is given as
  - $Y(S) / U(S) = 2S^2 + 8S + 7 / (S+1)(S+2)^2.$