Reg. No.:					

**Question Paper Code: 53503** 

## B.E. / B.Tech. DEGREE EXAMINATION, MAY 2018

Third Semester

Electronics and Instrumentation Engineering

## 15UEI303 - SENSORS AND TRANSDUCERS

(Common to Instrumentation and Control Engineering)

(Regulation 2015)

Duration: Three hours Maximum: 100 Marks

## **Answer ALL Questions**

PART A -  $(10 \times 1 = 10 \text{ Marks})$ 

- 1. The voltage of a circuit is measured by a voltmeter having an input impedance comparable with the output impedance of the circuit thereby causing error in voltage measurement. This error may be called
  - (a) Gross Error

- (b) Random Error
- (c) Error caused by misuse of instrument
- (d) Error caused by loading effect
- 2. Uncertainty distribution is used for
  - (a) analysis of multi-sample data
  - (b) analysis of single-sample data
  - (c) analysis of both single and multi sample data
  - (d) none of these
- 3. In measurement systems, which of the following static characteristics are desirable
  - (a) Accuracy

(b) Sensitivity

(c) Reproducibility

(d) All of the above

- 4. Example for zero order transducer is
  - (a) potentiometer

(b) thermistor

(c) resistance thermometer

(d) strain gauge

5.	Dummy strain gauges	are used for						
	(b) increasing the	of temperature changes sensitivity of bridge in v for different expansion strain gauges		luded				
6.	Thermocouples are							
	<ul><li>(a) Passive transd</li><li>(c) Both active an</li></ul>	ucers ad passive transducers	<ul><li>(b) Active transducers</li><li>(d) Output transducers</li></ul>					
7.	The principle of operation of LVDT is based on the variation of							
	<ul><li>(a) Self Inductance</li><li>(c) Reluctance</li></ul>	ce	<ul><li>(b) Mutual Inductance</li><li>(d) Permanence</li></ul>					
8.	SQUID stands for							
	(b) Superconduct	ity Interference Device ing Quantum Interferenc Intermediate Device	e Device					
9. An inductive proximity sensor reduces sensing range upto								
	(a) 70%	(b) 80%	(c) 60%	(d) 50%				
10.	MEMS stands for							
	(b) Macro Electro	lectric Micro System onic-Mechanical System -Mechanical System						
		PART - B (5 x 2 =	= 10 Marks)					
11.	What do you mean by	static calibration?						
12.	Differentiate range an	d span.						
13.	Define gauge factor.							
14.	Write the applications	s of Hall effect transduce	er.					
15.	Name any four applic	ations of NANO sensors	S.					

## PART - C (5 x 16 = 80 Marks)

(a)	(i) Explain the various measurement standards in details.	(8)
	(ii) Summarize the classification of errors in measuring instruments.	(8)
	Or	
(b)	Explain the criteria for selection of transducer for a particular application.	(16)
(a)	Solve the under damped second order for a step input and obtain the response of system.	of the (16)
	Or	
(b)	Discuss in detail about the static characteristics of transducers with suitable sketch	ches. (16)
(a)	Describe the construction of different types of strain gauges and working princ	eiple. (16)
	Or	
(b)	Describe the principle of operation, construction details, characteristics applications of LVDT.	and (16)
(a)	With neat sketch explain the working of a fiber optic displacement transducer.	(16)
	Or	
(b)	Brief explain the operation of Hall-effect transducer. Also explain its advantages applications.	s and (16)
(a)	Explain in detail about the measurement of relative motion and absolute mousing seismic instruments.	otion (16)
	Or	
(b)	Write short notes on:	
	(i) Vibration sensor	(8)
	(ii) Humidity sensor	(8)
	<ul><li>(b)</li><li>(a)</li><li>(b)</li><li>(a)</li><li>(b)</li></ul>	Or  (b) Explain the criteria for selection of transducer for a particular application.  (a) Solve the under damped second order for a step input and obtain the response of system.  Or  (b) Discuss in detail about the static characteristics of transducers with suitable skets.  Or  Or  (b) Describe the construction of different types of strain gauges and working prince.  Or  (b) Describe the principle of operation, construction details, characteristics applications of LVDT.  (a) With neat sketch explain the working of a fiber optic displacement transducer.  Or  (b) Brief explain the operation of Hall-effect transducer. Also explain its advantages applications.  (a) Explain in detail about the measurement of relative motion and absolute measurements.  Or  (b) Write short notes on:  (i) Vibration sensor