

14/6/16 FN

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Question Paper Code : 51765

B.E./B. Tech. DEGREE EXAMINATION, MAY/JUNE 2016

Sixth Semester

Computer Science and Engineering

IT 2354/IT 64/ 10144 IT 605/10144 CSE 26 – EMBEDDED SYSTEMS

(Common to Information Technology)

(Regulations 2008/2010)

Time : Three Hours

Maximum : 100 Marks

Answer ALL questions.

PART – A (10 × 2 = 20 Marks)

1. Distinguish an embedded system and a general purpose system.
2. List the types of 8051 instructions based on the operations and give one example to each.
3. How can we use the EQU pseudo-op to define a symbolic name for the memory location of I/O device ?
4. Define cache miss penalty.
5. Differentiate between task and process.
6. When a program is said to be re-entrant ?
7. Write a routine to change the state of an LED.
8. Write the features of an Interrupt Service Routine.
9. Mention the design goals of embedded systems.
10. What is a specification language ? Give an example.

PART – B (5 × 16 = 80 Marks)

11. (a) (i) Explain the data path of ARM processor with a neat diagram. (6)
(ii) Explain the embedded system design process of a Digital Camera. (10)

OR

- (b) (i) Draw the architecture diagram of 8051 microcontroller and explain each module. (8)
(ii) Write an ALP to generate a square wave of 1 KHz with a duty cycle of 40%. Use timer to generate delay. Crystal frequency used is 11.0592 MHz. (8)

12. (a) Explain the following :
(i) Prioritized device interrupts. (8)
(ii) Interrupts in ARM 7. (8)

OR

- (b) (i) Compare the behaviour of direct-mapped and set-associative caches with an example. (8)
(ii) Explain ARM two stage address translation. (8)

13. (a) (i) Describe the various CPU metrics. (8)
(ii) Explain the scheduling and its policies. (8)

OR

- (b) With appropriate diagrams, discuss about the Inter-Process Communication Mechanisms. (16)

14. (a) Explain multi-state system and function sequences. (16)

OR

- (b) Explain the advantage and disadvantage of programming embedded system in C and assembly language with example. (16)

15. (a) Describe the design details Elevator controller. (16)

OR

- (b) Explain the design of robot track control program. (16)