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Question Paper Code: 35032

B.E. / B.Tech. DEGREE EXAMINATION, NOV 2017

Fifth Semester

Electrical and Electronics Engineering

01UEE502 - CONTROL SYSTEMS

(Regulation 2013)

Duration: Three hours

Maximum: 100 Marks

Answer ALL Questions

PART A - (10 x 2 = 20 Marks)

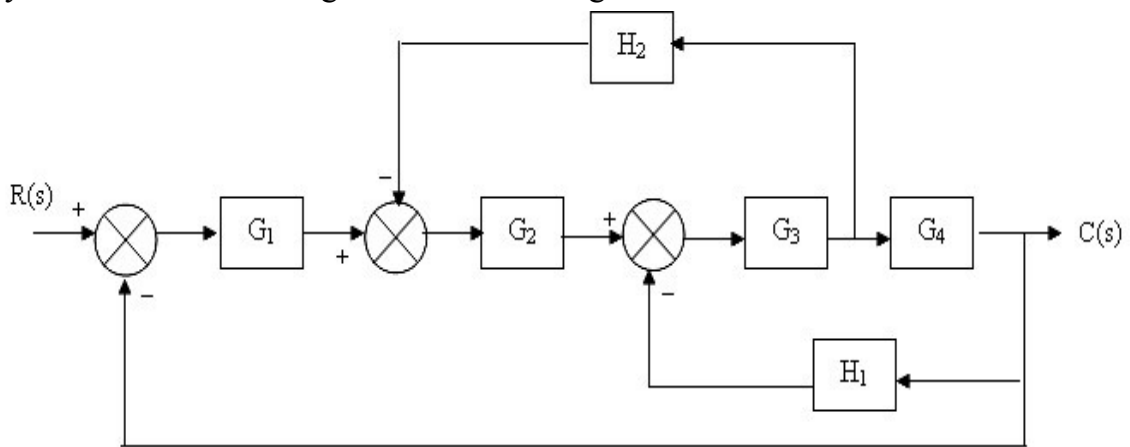
1. What is Synchro?
2. Define mathematical model of the system.
3. List the time domain specifications.
4. Write the transfer function of PID controller.
5. What are advantages of frequency response analysis?
6. Name the parameters which constitute the frequency domain specifications?
7. What is the necessary and sufficient condition for stability?
8. What is Nyquist stability criterion?
9. Define state and state variable.
10. Define controllability.

PART - B (5 x 16 = 80 Marks)

11. (a) Explain the open loop and closed loop system with an example. (16)

Or

- (b) Using block diagram reduction technique find the closed loop transfer function of the system whose block diagram is shown in figure. (16)



12. (a) Sketch the root locus of the system whose open loop transfer function is $G(s) = \frac{K}{s(s+2)(s+4)}$. Find the value of K so that the damping ratio of the closed loop system is 0.5. (16)

Or

- (b) The open loop transfer function of a unity feedback system is given by $G(s) = \frac{K(s+9)}{s(s^2+4s+11)}$. Sketch the root locus of the system. (16)

13. (a) Draw the Bode plot of the system whose open loop transfer function is given by $G(s) = \frac{75(1+0.2s)}{s(s^2+16s+100)}$. Determine phase margin and gain margin. (16)

Or

- (b) Consider a unity feedback system having an open loop transfer function $G(s) = \frac{K}{s(1+0.5s)(1+4s)}$. Sketch the polar plot and determine the value of K so that

(i) gain margin is 20 db

(ii) phase margin is 30° . (16)

14. (a) Use the routh stability criterion to determine the location of roots on the s-plane and hence the stability for the system represented by the characteristic equation

$$s^5 + 4s^4 + 8s^3 + 8s^2 + 7s + 4 = 0 . \quad (16)$$

Or

- (b) Determine the nyquist plot for the system whose open loop transfer function is,
 $G(S) H(S) = \frac{K}{S(S+2)(S+10)}$. Determine the range of K for which closed loop system is stable. (16)

15. (a) Determine the canonical state model of the system, whose transfer function is

$$T(s) = \frac{2(s+5)}{(s+2)(s+3)(s+4)} . \quad (16)$$

Or

- (b) A linear time-invariant system is characterized by homogeneous state equation.

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} . \text{ Compute the solution of the homogeneous equation, assuming}$$

the initial state vector, $X_0 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$. (16)

