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Reg. No. :					

Question Paper Code: 59051

B.E./B.Tech. DEGREE EXAMINATION, NOV 2018

Interdisciplinary Elective Course

Mechanical Engineering

15UGM951 – SMART MANUFACTURING

(Common to Information Technology)

(Regulation 2015)

Answer ALL Questions

		PART A - (10 x	1 = 10 Marks	
1.	Industry 2.0 related w	vith		CO1- R
	(a) Electrical drives		(b) Steam engine	
	(c) Cloud computing		(d) All of these	
2.	Cloud computing rela	ated with		CO1- R
	(a) Industry 1.0	(b) Industry 2.0	(c) Industry 3.0	(d) Industry 4.0
3.	is no	t an example of additiv	ve manufacturing.	CO2- R
	(a) CNC	(b) SLA	(c) SLS	(d) DMLS
4.	Additive Manufactur technologies that buil	• • • •	name to describe the	CO2- R
	(a) 3D objects	(b) 2D objects	(c) Both (a) and (b)	(d) None of the above
5.	Which of the following	ng work is done by Ger	neral purpose robot?	CO3- R
	(a) Part picking	(b) Welding	(c) Spray painting	(d) All of the above

6.		In which of the following operations Continuous Path System is used							
	(a) Pick and Place			(b) Loading and Unl	oading	5			
	(c) (Continuous weldin	(d) All of the above	(d) All of the above					
7.	Wha	at is the size of the	e IPv6 addressed?				CO4- R		
	(a) 3	32 bits	(b) 64 bits	(c) 128 bits	(d) 25	56 bits			
8.	Whi	ich one is not an e			CO4- R				
	(a) I	People	(b) Process	(c) Security	(d) T	hings			
9.	Exa	mple for private c	loud vendor	-			CO5- R		
	(a) l	Eucalyptus	(b) Open nebula	(c) Both a & b	(d) N	one of the	above		
10.	Froi	m the following w	hich is not a Saas pla	atform			CO5- R		
	(a) J	Jitterbit	(b) Boomi	(c) Snap logic	(d) N	one of the	above		
			PART - B (5	x 2= 10Marks)					
11.	Def	ine CPS.					CO1- R		
12.	. Classify additive manufacturing.								
13.	. List the various types of Robot coordination systems.								
14.	Praw the future ICT-empowered interaction-rich Smart Grid.								
15.	. Write short notes about Amazon Web service.								
			PART – C ((5 x 16= 80Marks)					
16.	(a)	Explain about C	yber Physical System			CO1-U	(16)		
	` /	•	Or				`		
	(b)	Explain about In	ternet of Things with	necessary diagram.		CO1-U	(16)		
17.	(a)	-	advantages and disad	ing method with neat s lvantages of this method		CO2-U	(16)		
	(1-)	W/:41 1 4	Or	fatanial Tatting and 1	1	CO2 II	(1.6)		
	(b)		en explain about M ntages and disadvanta	faterial Jetting method	ana	CO2-U	(16)		

18.	(a)	Assume the future robotic technology and tasks.	CO3-Ana	(16)
		Or		
	(b)	Identify and discuss about social and labor issues related to robotic applications in modern manufacturing industry.	CO3-Ana	(16)
19.	(a)	Examine the applicability of future ICT-empowered interaction in rich Smart Grid.	CO4- App	(16)
		Or		
	(b)	Inspect the difficulties in implementing commercial building automation in the future.	CO4- App	(16)
20.	(a)	Compare any four Iaas providers with respect to hypervisor technology, billing, scaling, and processor and API access.	CO5- Ana	(16)
		Or		
	(b)	Compare various Saas integration platforms	CO5- Ana	(16)