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Reg. No.:					

Question Paper Code: 37703

B.E. / B.Tech. DEGREE EXAMINATION, DEC 2020

Seventh Semester

Mechanical Engineering

01UME703 - MECHATRONICS

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	(Regulation 2013)								
D	Ouration: One hour Maximum: 30 Marks								
	PART A - $(6 \times 1 = 6 \text{ Marks})$								
	(Answer any six of the following questions)								
1.	1. A good example of standalone Mechatronics system is								
	(a) Washing machine (b) CIM (c) humanoid robot (d) aircraft								
2.	Inductive proximity sensors can be effective only when the objects are of materials.								
3.	(a) Ferro magnetic (b) Diamagnetic (c) Paramagnetic (d) All of the above Which energy is converted into mechanical energy by the hydraulic cylinders?								
	(a) Hydrostatic energy (b) Hydrodynamic energy								
	(c) Electrical energy (d) None of the above								
4.	What is the function of electric actuator?								
	(a) Converts electrical energy into mechanical energy								
	(b) Converts mechanical torque into electrical energy								
	(c) Converts mechanical energy into mechanical torque								

(b) AC motor controller

(d) AC & DC controllers

(d) None of the above

5. Variable speed cannot be obtained with _____.

(a) DC motors controller(c) Soft starter controller

6	of PLCs can be done in very little time	2.			
	(a) Programming	(b) Installation			
	(c) Commissioning	(d) All of the above			
7. PLC	es are programmed using what language?				
	(a) Natural Language such as English	(b) C-language			
	(c) Relay-ladder logic	(d) None of the above			
8	PLC programming methods.				
	(a) Structured text	(b) Ladder diagrams			
	(c) Function block diagram	(d) All of the above			
9. Eng	gine management system is made up of				
	(a) Sensors	(b) Actuators			
	(c) Microprocessor	(d) All of the above			
10. Ser	nsors detect a				
	(a) Mechanical condition	(b) Chemical state			
	(c) Temperature conditioning	(d) All of the above			
	PART – B (3 x 8	3= 24 Marks)			
	(Answer any three of the	e following questions)			
11.	Explain the terms used to define the performance of a measurement system.				
12.	Explain about the primary functions of mechanical actuation systems.				
13.	Explain in detail Gain-scheduled and self- turning adaptive control system with suitable block diagram.				
14.	Explain the factors considered for the selection of a PLC. (8)				
15.	Discuss in detail, various design factors to be considered while designing a mobile robot? (8)				