| Reg. No. : | | | | | | | | | |
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Question Paper Code: 49410

B.E. / B.Tech. DEGREE EXAMINATION, DEC 2020

Elective

Electronics and Communication Engineering

14UEC910 - DIGITAL IMAGE PROCESSING

(Regulation 2014)

Duration: 1:15hrs

Maximum: 30 Marks

PART A - $(6 \times 1 = 6 \text{ Marks})$

(Answer any six of the following questions)

| 1. Amount of energy that flows from the light source is | | | | | | |
|--|---------------------|-----------------------|-----------------|--|--|--|
| (a) Brightness | (b) Radiance | (c) Luminance | (d) Reflectance | | | |
| 2. Intensity levels in 8-bit image are | | | | | | |
| (a) 128 | (b) 255 | (c) 256 | (d) 512 | | | |
| 3. Smoothing filters are mostly used in | | | | | | |
| (a) Blurring | (b) Noise reduction | (c) Contrast | (d) A and B | | | |
| 4. The method used to generate a processed image that has a constant histogram is called | | | | | | |
| (a)Histogram enhancement (b) Histogram matching | | | | | | |
| (c) Histogram normalization (d) Histogram equalization | | | | | | |
| 5. Image restoration and image enhancement is performed in | | | | | | |
| (a) Both thee spatial and | d frequency (b) B | oth frequency and tir | ne | | | |
| (c) Only frequency dom | ain (d) Or | nly spatial domain | | | | |

| 6. | Minimum mean square error filter is otherwise called as | | | | | |
|---|---|-----------------------|--------------------------------|-------------------------|--|--|
| | (a)Low pass filter | (b) High pass filter | (c) Inverse filter | (d) Least square filter | | |
| 7. | Canny edge detache | er is | | | | |
| | (a) Isotropic defecto | or | (b) Non isotropic defector | | | |
| | (c) Does not produc | ce long thin contours | (d) Uses the second derivative | | | |
| 8. Gradient computation is more useful in | | | | | | |
| | (a) Point detection | n (b) Edge detection | on (c) Area detection | (d) Line detection | | |
| 9. The Hit-or-Miss transformation is used for shape | | | | | | |
| | (a) Removal | (b) detection | (c) Compression | (d) Decompression | | |
| 10. | 10. Third moment is defined as the meaner of | | | | | |
| | (a) Flatness | | (b) Skewness | | | |
| | (c) Sharpness | | (d) Variability of the image | | | |

PART – B (3 x 8= 24 Marks)

(Answer any three of the following questions)

| 11. Explain in detail elements of visual perception. | (8) | |
|--|-----|--|
| 12. Write notes on smoothing spatial filtering | (8) | |
| 13. Describe in detail the geometrical transformation applied to the pixels to restore the | | |
| image | (8) | |
| 14. Summarize region based image segmentation techniques. | (8) | |
| 15. Explain in detail various image representation approaches | (8) | |

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