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B.E. / B.Tech. DEGREE EXAMINATION, NOV 2020

Seventh Semester

Biomedical Engineering

15UBM702 – HUMAN ASSISTIVE DEVICES

		(Regulati	on 2015)			
Dura	ation: One hours			Maximum: 30Marks		
		PART A - (6 2	x 1 = 6 Marks			
		(Answer any six of th	e following questions)			
1.	The record used to deheart is beating is call	•	es in the heart muscle as	the CO1- R		
	(a) Echocardiogram		(b) Electrocardiogram			
	(c) Electroencephalo	gram	(d) Sphygmomanometer	•		
2.	120 to 140 mm of me	nal	CO1- U			
	(a) Systolic pressure		(b) Diastolic pressure			
	(c) Peristalsis pressur	re	(d) Water pressure			
3.	In peritoneal dialysis the clean fluid is call		ne dirty fluid and putting	g in CO2-R		
	(a) A replacement	(b) A hemo cleaning	(c) An exchange	(d) A dialysate		
4.	How many times a w	veek dialysis must be d	one	CO2- R		
	(a) Every day	(b) Once a week	(c) Twice a day	(d) Thrice a week		
5.	The tiny hairs that ke	eep mucus and dirt out	of your lungs are called	CO3- U		
	(a) Lung hair	(b) Stubble	(c) Bronchitis	(d) Cilia		
6.	When you inhale you	ır lungs		CO3- R		
	(a) Inflate	(b) Turn purple	(c) Deflate	(d) Disappear		
7.	Devices that assist a	person with walking a	re classified as dev	vices. CO4- U		
	(a) Ambulatory		(b) Ankle-foot			
	(c) Spinal		(d) Knee-ankle-foot			
8.	Fusion of a joint to prevent motion is termed as					
	(a) Arthrodesis	(b) Osteotomy	(c) Arthroplasty (d) Arthrotomy		

9.	The physical structure of Robot which moves around is called CO5				
	(a) Manipulators		(b) End effectors		
	(c) Joints		(d) Links		
10. Which of the following terms is not one of the basic parts of a robots?					
	(a) Peripheral tools	(b) End effectors	(c) Controller	(d) Drive	
		PART - B (3	x 8= 24 Marks)		
		(Answer any three of	the following questions	s)	
11.	. Explain the pulsatile and continuous type blood pump in oxygenators. Co				(8)
12.	. Discuss the different types of dialyzers with necessary diagrams. CO2				(8)
13.	. Discuss the various levels of deafness and hearing aids. CO3-				a (8)
14.	Describe about types of haptic devices with a neat block diagram.				a (8)
15.	5. Describe the flexion and extension in robotics.				a (8)