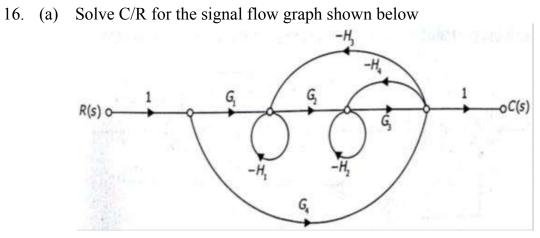
A		Reg. No. :										
]	Question Pa	per C	ode	: 59	9404	1					
	B.E. / I	B.Tech. DEGREE	EXAM	INA	TIC	DN, N	IOV	20	19			
		E	lective									
	E	lectronics and Com	nmunic	ation	Er	ngine	erin	g				
	15UI	EC904–LINEAR C	CONTR	OL	EN	GINE	EER	ING				
		(Regul	lation 2	015)								
Dur	ration: Three hours	Answer A	ALL Qu	iestic	ons			N	laxi	mum	: 100) Ma
		PART A - (1	0 x 1 =	10 N	Marl	ks)						
1.	Which among the follo system?	owing represents an	n illustr	atior	n of	close	ed lo	oop				CO
	(a) Automatic washing(c) Bread toaster	machine				tomat ctric				on		
2.	A closed loop system is distinguished from open loop system by which CO of the following?											
	(a) Servomechanism	(b) Feedback		(c) Output patt				patte	rn	(d) I	nput	patte
3.	By which of the following the system response can be tested better? CO2											
	(a) Ramp input signal			(b) Sinusoidal input signal								
	(c) Unit impulse input signal			(d) Exponentially decaying signal								
4.	Which controller has the potential to eliminate/overcome the drawbackCO2of offset in proportional controllers?CO2											
	(a) P-I	(b) P-D		(c)	Bot	h a a	nd t)	(d)	None	e of t	he al
5.	Which unit is adopted	for magnitude mea	asureme	ent in	n Bc	ode pl	lots	?				CO
	(a) Degree	(b) Decimal			(c)	Dec	ibel			(d) I	Devia	ation
6.	The magnitude & phas steady state output is c	-				_inpu	ıt an	d the	e			CO
	(a) Step	(b) Ramp	uomun		(c)) Sint	isoi	dal		(d) I	Parab	olic

7.	Root locus specifies the movement of closed loop poles especially when the gain of system								
	(a) Remains constant		(b) Exhibit variation	ons					
	(c) Gives zero feedback		(d) Gives infinite p	oles					
8.	In Routh array, if zero is found in the first column, then by which term CO4 it needs to be replaced?								
	(a) δ	(b) η	(c) σ	(d) ε					
9.	Which among the following plays a crucial role in determining the state CO5- of dynamic system?								
	(a) State variables	(b) State vector	(c) State space	(d) State scalar					
10.	State space analysis is a	CO5- R							
	(a) Zero	(b) Non-zero	(c) Equal	(d) Not equal					
PART - B (5 x 2= 10 Marks)									
11.	State Mason's gain form	CO1- R							
12.	What will be the respon	CO2- R							
13.	What are the characteris	CO3- R							
14.	What is dominant pole?	CO4- R							
15.	Define the state and stat	CO5- R							

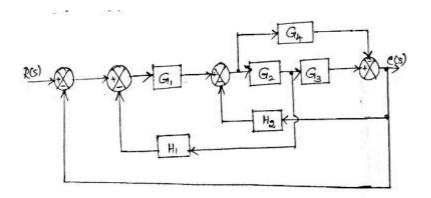
PART – C (5 x 16= 80 Marks)



Or

CO1 App (16)

(b) How could you determine the Transfer Function of the system CO1 App (16) Shown in the figure below?



17. (a) Draw the block diagram of second order system. Classify it. CO2- App (16) Derive the time response of any one of the damped systems for unit step input.

Or

- (b) The open loop transfer function of a unity feedback system is CO2- App (16) given by G(S) = 20/S(S+2). The input function is $r(t) = 2 + 3t + t^2$. Examine the generalized error coefficient and steady state error.
- 18. (a) Given $G(S) = ke^{-0.2S}/S(S+2)(S+8)$ CO3- App (16) Draw the Bode plot and find K for the following two cases when (i) Gain margin equal to 6db
 - (ii) Phase margin equal to 45°.

Or

- (b) The open loop transfer function of a unity feedback system is CO3- App (16) given by $G(S) = 1 / S^2$ (1+S) (1+2S). Sketch the polar plot and determine the gain and phase margin.
- 19. (a) Define Stability. With an example, explain the steps to be CO4- App (16) followed for Routh-Hurwitz criterion.

Or

(b) The open loop transfer function of a unity feedback system is CO4- App (16) given by $(S) = (S+9)/S(S^2+4S+11)$. Sketch the root locus of the system and the evaluate the system stability with respect to their location of poles.

20. (a) A system is represented by State equation

 $\dot{X} = Ax + Bu$ and output equation

Y=Cx + Du Where

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -6 & -11 & -6 \end{bmatrix}; \qquad B = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}; \qquad C = \begin{bmatrix} 10 & 5 & 1 \end{bmatrix}$$

Verify the controllability and observability of the control system.

Or

(b) Determine the state variable representation of the system whose CO5- App (16) transfer function is given as $Y(S) / U(S) = 2S^2 + 8S + 7 / (S+1)(S+2)^2$.

CO5- App

(16)