	Reg. No. :									
	Question Pape	er Cod	e: 494	10						
B.E	. / B.Tech. DEGREE	EXAMI	NATIC)N, N	OV 2	019				
	E	lective								
	Electronics and Con	nmunica	tion En	ginee	ring					
	14UEC910 - DIGITA	L IMAC	JE PRC	OCESS	SING	r				
	(Regul	ation 20	14)							
Duration: Three hours	(8		,			Max	imur	m• 1()0 M	larks
	Answer A	JI Oue	stions						,0 10	.unito
		_								
	PART A - (1			(S)						
1. Amount of energy th	hat flows from the light	nt source	÷ 1S							
(a) Brightness	s (b) Radian	nce	(c) L	Lumin	ance		(d)) Ref	lecta	ance
2. Intensity levels in 8	-bit image are									
(a) 128	(b) 255		(c) 25	6		((d) 5	12		
3. Smoothing filters are	e mostly used in									
(a) Blurring	(b) Noise re	duction	(c) C	ontras	st		(d)	A an	nd B	
4. The method used to	generate a processed	image th	at has a	a cons	tant ł	nistog	gram	is ca	alled	
(a)Histogram enhancement (b) Histogram matching										
(c) Histogram	normalization	(d) Hist	ogram e	equali	zatio	n				
5. Image restoration as	nd image enhancemer	it is perf	ormed i	n						
(a) Both thee spatial and frequency (b) Both frequency and time										
(c) Only freque	ency domain	(d) O	nly spa	tial do	omain	L				

6.	Minimum mean square error filter is otherwise called as									
	(a)Low pass filter	(b) High pass filter	(c) Inverse filter	(d) Least square filter						
7.	Canny edge detacher is									
	(a) Isotropic defecto	or	(b) Non isotropic defector							
	(c) Does not produc	e long thin contours	(d) Uses the second derivative							
8. Gradient computation is more useful in										
	(a) Point detection	n (b) Edge detectio	n (c) Area detection	(d) Line detection						
9. The Hit-or-Miss transformation is used for shape										
	(a) Removal	(b) detection	(c) Compression	(d) Decompression						
10.	10. Third moment is defined as the meaner of									
	(a) Flatness		(b) Skewness							
	(c) Sharpness		(d) Variability of the image							

PART - B (5 x 2 = 10 Marks)

- 11. Describe the characterization of light.
- 12. What is the need for Directional Smoothing in image processing?
- 13. Give the comparison of various noise models.
- 14. Write the process of edge linking and boundary detection.
- 15. Write notes on polygonal approximation.

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PART - C (5 x
$$16 = 80$$
 Marks)

16. (a) Explain in detail elements of visual perception.

Or

- (b) Explain in detail about KL transform of images with its properties. Also explain fast KL transform. (16)
- 17. (a) Write notes on smoothing spatial filtering (16)

(16)

(b) Explain the types of gray level transformation used for image enhancement					
 18. (a) Describe in detail the geometrical transformation applied to the pixels to restoring. Or (b) Evaluate the image restoration with the help of spatial filtering. 	re the (16) (16)				
19. (a) Summarize region based image segmentation techniques. Or	(16)				
(b) How edge detection is performed in digital images by					
 (i) Gradient Operator. (ii) Maar-Hildreth edge detector. (iii) The Canny edge detector. 	(4) (6) (6)				
 20. (a) Describe the following (i) Convex Hull. (ii) Skeletons. 	(4)				
(ii) Skeletons.(iii) Pruning.Or	(6) (6)				

Or

(b) Explain in detail various image representation approaches (16)

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