Α		Reg. No. :										
		Question Pa	per C	ode:	5650	03						
	B.E. / I		EXAM	INATI	ON, I	NOV	<b>.</b> 201	9				
		Sixth	Semes	ter	,							
	E	lectronics and Inst	rumenta	tion E	ngine	ering	Ţ					
		15UEI603-PR	OCESS	CONT	ROL	,						
		(Regul	ation 20	)15)								
D	ouration: Three hours			,		N	Лахі	mun	n: 10	0 Ma	rks	
		Answer A	ALL Qu	estions								
		PART A - (1	0 x 1 =	10 Ma	rks)							
1.	Which of the follow instrument?	ving are the dyn	amic o	charact	eristic	cs o	f ar	1			CO	l- R
	(a) Reproducibility	(b) Sensitiv	vity	(c) ]	Dead	zone	<b>;</b>	(	d) Fi	delity	/	
2.	Thermocouple in a thermal well behaves as a true CO1- F							l- R				
	(a) first order system (b) multipl				ole fi	first order system						
	(c) second order system (overdamped) (d) second order system						ysten	stem (underdamped)				
3.	What type of controller is displayed by the equation below? CO2- App								рр			
	$c(t) = K_c[e(t) + \frac{1}{T_c} \int e(t)dt]$											
	(a) Feed forward	(b) Derivative	(0	) PID				(d In	) tegra	Proj al	porti	onal
4.	controller is an example of discontinuous controller mode CO2- U								2- U			
	(a) Proportional control (b) Integral contr			rol								
	(c) Derivative control (d) ON/OFF control											
5.	Control is the satisfactory control for temperature process						cess				CO	3- U
	(a) PID	(b) PI	(c	) PD		-		(d	) P			

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6.	Use of	CO3- R						
	(a) elimination of offset			(b) reduction of offset				
	(c) reduction of stability time		(d) none of these					
7.	The pl	nenomenon of	cavitation is related to		CO4- R			
	(a) Pas	scal law	(b) Bernouli's theorem	(c) Newton's law	(d) Hooks law			
8.	In Ele by wh	ctro-Pneumaticities of the following the second sec	c Direction control valves owing?	s the actuation is done	CO4- R			
	(a) Le	ver	(b) Push button	(c) Solenoid	(d) Relay			
9.	The control configuration with primary loop and secondary loop is CO known as							
	(a) Ca	scade control		(b) Split range control				
	(c) Ra	tio control		(d) Feed forward control	bl			
10.	Control valve sizing depends on				CO5- R			
	(a) Cv	factor	(b) Flow rate	(c) Fluid property	(d) Line pressure			
			PART – B (5 x 2	2= 10Marks)				
11.	Differ	CO1- U						
12.	Draw the circuit for electronic PI controller.							
13.	What are the parameters required to design a best controller?							
14.	List ar	CO4- R						
15.	Show the advantage of cascade control over conventional control				CO5- R			
			PART - C (5 x)	x 16= 80Marks)				
16.	(a)	Derive the t tank system	ransfer function for inte	eractive capacities of tw	to CO1-App (16)			
	( <b>b</b> )	Describe e si	Or male thermal system in w	which incoming liquid is	CO1 U (16)			
	(0)	heated by the	heater in the tank and go	bing out with higher	(10)			
		temperature. thermal proce	Develop first order trans	fer function of the				
17.	(a)	Describe the controller.	e characteristics of P,	PI and PID modes of	of CO2- App (16)			

Or

	(b)	(i) Illustrate the need and benefit of each component of composite PID controller.	CO2- U	(8)
		(ii) Draw and explain pneumatic proportional controller.	CO2- U	(8)
18.	(a)	Discuss the controller settings using Ziegler-Nichols continuous cycling method and write its limitations. Or	CO3- U	(16)
	(b)	Explain process reaction curve method & damped oscillation method	CO3- Ana	(16)
19.	(a)	Explain the operation of pneumatic actuators with and without valve positioner	CO4- U	(16)
		Or		
	(b)	(i) Illustrate the inherent and installed characteristics of control valve	CO4-U	(8)
		(ii) Summarize the factors to be considered before the selection of control valve for a given application.	CO4-U	(8)
20.	(a)	(i) Explain the concept of ratio control with an example	CO5- U	(8)
		(ii) What is split range control? Describe a situation when you could use split range control	CO5- U	(8)
		Or		
	(b)	Illustrate the operation of split range controller and inferential controller.	CO5- U	(16)