

12. (a) (i) Obtain the transformation matrices for orthographic projection. (5)
(ii) Rotate the rectangle formed by points $P_0 (1,1)$, $P_1 (2, 1)$, $P_2 (2, 3)$, $P_3 (1, 3)$ by 30° CCW about the point $S(3,2)$ using transformation matrices. (11)

Or

- (b) Explain in detail the structure of the OPITZ system for parts classification and coding.
13. (a) Describe the methods involved in set up planning. Explain the method of determining the number of set ups in a 'Chuck only' component.

Or

- (b) What is a pocket with respect to process planning? Explain the steps involved in pocket identification procedure considering an example rotating part.
14. (a) Discuss the role of decision tables, decision trees and artificial intelligence in implementing CAPP.

Or

- (b) (i) Briefly explain the benefits of CAPP. (5)
(ii) Explain the information flow in a retrieval type computer aided process planning system. Specify the four options provided in MIPLAN system to create the process plan and the subsequent generation of route sheet. (11)
15. (a) Explain the framework of an integrated process planning system with the aid of schematic diagrams.

Or

- (b) Describe the data structure and communication methods adopted in totally integrated process planning systems.