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Reg. No. :					

Question Paper Code: 57703

B.E. / B.Tech. DEGREE EXAMINATION, APRIL 2019

Seventh Semester

Mechanical Engineering

15UME703- MECHATRONICS

		(Regulation	on 2015)		
Dura	ation: Three hours		Maximum: 1	00 Marks	
		Answer ALI	Questions		
		PART A - (10 x	1 = 10 Marks)		
1.	The working of steppe		CO1- R		
	(a) Open loop system		(b) Closed loop system		
	(c) Sequential system		(d) None of these		
2.	Inductive pressure tra	nsducers are used to m	easure		CO1- R
	(a) Temperature	(b) Flow	(c) Pressure	(d) Level	
3.	Which element used power.	l to converts hydraul	ic power into mechanical		CO2- U
	(a) compressor		(b) Pump		
	(c) Actuator		(d) Convertors		
4.	Identify the belt driv	ve that doesn't under	go slip while transmitting		CO3- U
	(a) Timing	(b) Round	(c) V- Belt	(d) Cross	
5.	Which of the follow block?	ing is not an element	of a mechanical building		CO3- R
	(a) Capacitor	(b) Dashpot	(c) Mass	(d) Spring	,
6.	The corrective measure proportional mode is	res taken by a control	ler when it is operated in a		CO3- U
	(a) K _p e	(b) K _n /e	(c) $1/K_{p}$	(d) e/K _n	

7.	PLC	can be	in plant to change	the sequence of operation		CO4- R
	(a) (Only programmed		(b) only reprogrammed		
	(c) I	Programmed and re	eprogrammed	(d) able to give a set point		
8.		ounter that starts from is known as the	rom a specified numb	er and increments down to		CO4- R
	(a) U	Up counter		(b) Down counter		
	(c) I	Reset counter		(d) Synchronizing counter		
9.	In g	eneral, design proc	ess starts with	of the product		CO5- R
	(a) A	Analysis	(b) Solution	(c) Resale value	(d) Need	
10.		ich sensor is used aust gas	in engine manageme	nt system to measure burne		CO5- R
	(a) (Oxygen sensor	(b) temperature senso	or (c) speed sensor	(d) Need	
			PART - B (5 x	2= 10Marks)		
11.	Wha	at is dynamic braki	ng?			CO1- R
12.	. Write the objectives of Directional Control Valves.					
13.	. Interpret thermal capacitance in thermal system building block					
14.	Exp	lain delay ON and	delay OFF timer with	ladder diagrams		CO4- R
15.	6. What is a windscreen wiper					
			PART - C (5	x 16= 80Marks)		
16.	(a)	Explain in detail used in mechatron		of measurement systems	CO1- U	(16)
	(b)	(i) Interpret how of	does LVDT measure	displacement.	CO1- U	(4)
		(a) Pressur	rature sensor	ensors:	CO1- U	(12)
17.	(a)		sketch. List the men	of a pneumatic actuation rits and demerits of using	CO2- U	(16)

Or

	(b)	Explain with neat sketches the working of any three hydraulic pumps	CO2- U	(16)
18.	(a)	Design building blocks for translational and rotational system. Also, derive the relationship between their input and output. Or	CO3- App	(16)
	(b)	Explain with neat example of microprocessor based controller	CO3- App	(16)
19.	(a)	Discuss how AND, OR, NOR and NAND systems can be formed with ladder diagram	CO4- U	(16)
	(b)	Summarize how data are handled in PLC with necessary illustrations.	CO4- U	(16)
20.	(a)	Design a autonomous mobile robot using mechatronics elements Or	CO5- App	(16)
	(b)	Illustrate the application of mechatronics system in engine management of a modern car.	CO5- App	(16)