| Reg. No.: | | | | | |
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Question Paper Code: 47703

B.E. / B.Tech. DEGREE EXAMINATION, APRIL 2019

Seventh Semester

Mechanical Engineering

14UME703 - MECHATRONICS

(Regulation 2014)

| Duration: Three hours | Maximum: 100 Marks |
|-----------------------|--------------------|
| | |

Answer ALL Questions

| | PA | RT A - (10 x | 1 = 10 Marks | | | | |
|--|--|--|---|---|--|--|--|
| A good example of standalone Mechatronics system is | | | | | | | |
| (a) Washing machine | | (b) CIM | (c) humanoid robot | (d) aircraft | | | |
| Inductive proximit | y sensors ca | n be effective | only when the objects | s are of | | | |
| materials. | | | | | | | |
| (a) Ferro magn | netic (b) I | Diamagnetic | (c) Paramagnetic | (d) All of the above | | | |
| 3. The type of drive suitable for high torque application is | | | | | | | |
| (a) Pneumatic dri | ve (b) El | ectric drive | (c) hydraulic drive | (d) Vector drive | | | |
| What is the functio | n of electric | actuator? | | | | | |
| (a) Converts electrical energy into mechanical energy | | | | | | | |
| | (a) Washing no Inductive proximit materials. (a) Ferro magnature The type of drive (a) Pneumatic drive What is the function | A good example of standalone (a) Washing machine Inductive proximity sensors camaterials. (a) Ferro magnetic (b) In the type of drive suitable for (a) Pneumatic drive (b) El What is the function of electric | A good example of standalone Mechatronics (a) Washing machine (b) CIM Inductive proximity sensors can be effective materials. (a) Ferro magnetic (b) Diamagnetic The type of drive suitable for high torque at (a) Pneumatic drive (b) Electric drive What is the function of electric actuator? | (a) Washing machine (b) CIM (c) humanoid robot Inductive proximity sensors can be effective only when the objects materials. (a) Ferro magnetic (b) Diamagnetic (c) Paramagnetic The type of drive suitable for high torque application is (a) Pneumatic drive (b) Electric drive (c) hydraulic drive (d) What is the function of electric actuator? | | | |

- (b) Converts mechanical torque into electrical energy
- (c) Converts mechanical energy into mechanical torque
- (d) None of the above

| 5. | The basic building blocks of the models use systems are | CO3-R | | | | | |
|-----|---|-----------------------------|-------------|--|--|--|--|
| | (a) spring, mass & dashpot | (b) voltage, current & resi | stance | | | | |
| | (c) resistance, capacitance & inductance | (d) force, resistance & vib | oration | | | | |
| 6 | of PLCs can be done in very little time | . | | | | | |
| | (a) Programming | (b) Installation | | | | | |
| | (c) Commissioning | (d) All of the above | | | | | |
| 7. | PLC operates with vo | ltage. | | | | | |
| | (a) 24 DC (b) 5 VDC | (c) 440 VAC | (d) 240 VAC | | | | |
| 8. | . For an AND logic function in PLC, X1 and X2 are the input switches then the output produced when the switches | | | | | | |
| | (a) X1 ON and X2 OFF | (b) X1 OFF and X2 ON | | | | | |
| | (c) Both X1 and X2 ON | (d) Either X1 or X2 ON | | | | | |
| 9. | Engine management system is made up of | | | | | | |
| | (a) Sensors | (b) Actuators | | | | | |
| | (c) Microprocessor | (d) All of the above | | | | | |
| 10. | Sensors detect a | | | | | | |
| | (a) Mechanical condition | (b) Chemical state | | | | | |
| | (c) Temperature conditioning | (d) All of the above | | | | | |
| | PART - B (5 x $2 =$ | 10 Marks) | | | | | |
| 11. | List any four types of sensors and mentioned | their features. | | | | | |
| 12. | What is servo motor? | | | | | | |
| 13. | What is a digital logic control? | | | | | | |
| 14. | List any four criteria for selection of PLC. | | | | | | |

15. What is engine management system?

| PART - C (5 x $16 = 80 \text{ Marks}$) | |
|--|-------|
| 16.(a) Explain in detail about various temperature sensors. | (16) |
| Or | |
| (b) With neat sketch explain various bonded type strain gauges. | (16) |
| 17. (a) Explain the four quadrant operation of a dc drive. | (16) |
| Or | |
| (b) Explain the four quadrant operation of a dc drive. | (16) |
| 18. (a) Compare the control system performance for a system with proportional co | ntrol |
| and a system with integral control | (16) |
| Or | |
| (b) Explain in detail about the mathematic modelling of rotational translational | |
| mechanical system. | (16) |
| 19. (a) Explain the features of programmable controller with a description of the | |
| instruction sets. | (16) |
| Or | |
| (b) Describe the basics of PLC programming with suitable illustrations. | (16) |
| 20.(a) (i) Explain in detail about various stages in designing Mechatronics systems. | (10) |
| (ii) Compare traditional and Mechatronics system. | (6) |

Or

(b) Present a case study pertaining to the design of a wireless surveillance balloon. (16)