Reg. No.:					

Question Paper Code: 54502

B.E. / B.Tech. DEGREE EXAMINATION, APRIL 2019

Third Semester

Electronics and Instrumentation Engineering

15UEI303 - SENSORS AND TRANSDUCERS

(Common to Instrumentation and Control Engineering)

(Regulation 2015)

Duration: Three hours Maximum: 100 Marks

Answer ALL Questions

PART A - $(10 \times 1 = 10 \text{ Marks})$

- 1. The voltage of a circuit is measured by a voltmeter having an input impedance comparable with the output impedance of the circuit thereby causing error in voltage measurement. This error may be called
 - (a) Gross Error

- (b) Random Error
- (c) Error caused by misuse of instrument
- (d) Error caused by loading effect
- 2. Uncertainty distribution is used for
 - (a) analysis of multi-sample data
 - (b) analysis of single-sample data
 - (c) analysis of both single and multi sample data
 - (d) none of these
- 3. In measurement systems, which of the following static characteristics are desirable
 - (a) Accuracy

(b) Sensitivity

(c) Reproducibility

- (d) All of the above
- 4. A pressure measurement instrument is calibrated between 10 bar and 250 bar. The scale span of the instrument is
 - (a) 10 bar
- (b) 250 bar
- (c) 240 bar
- (d) 260 bar

5.	Dummy strain gauges are	used for				
	(a) Compensation of t(b) increasing the sens(c) compensating for o(d) calibration of strain	sitivity of bridge in wl different expansion	nich they are included	d		
6.	Thermocouples are					
	(a) Passive transducer(c) Both active and pa		(b) Active transducers(d) Output transducers			
7.	A tachometer encoder has					
	(a) one output(c) three outputs		(b) two outputs(d) four outputs			
8.	Piezo-electric transducer v	work when we apply _	to it			
	(a) Mechanical force	(b) Vibrations	(c) Illuminations	(d) Heat		
9.	An inductive proximity se	nsor reduces sensing	range upto			
	(a) 70%	(b) 80%	(c) 60%	(d) 50%		
10.	Humidity can be measured	d using				
	(a) Rotameter	(b) Hygrometer	(c) Thermometer	(d) Anemometer		
		PART - B (5 x $2 = 1$	10 Marks)			
11.	Define unit.					
12.	Differentiate range and sp	an.				
13.	Define gauge factor.					
14.	Write the applications of I	Hall effect transducer.				
15.	Name any four application	ns of NANO sensors				
		PART - C (5 x 16 =	80 Marks)			

PART - C (5 x
$$16 = 80$$
 Marks)

16. (a) Explain in detail the various classifications of errors with examples and also discuss the methods of minimizing the errors. (16)

(b)	Explain the criteria for selection of transducer for a particular application.	(16)
(a)	Derive the time response of a second order under damped measuring system unit step input. Draw the response.	for a
	Or	
o)	Derive an equation for time response of a first order system when subjected to step input. Draw the response curves and find the dynamic errors.	uni (16)
(a)	Describe the construction of different types of strain gauges and working princ	ciple (16)
	Or	
(b)	Describe the principle of operation, construction details, characteristics applications of LVDT.	and (16)
(a)	With neat sketch explain the working of a fiber optic displacement transducer.	(16)
	Or	
(b)	Discuss the theory, working and application of Hall effect Transducer.	(16)
(a)	Describe the concepts and working of smart sensor with neat diagram.	(16)
	Or	
(b)	Explain the concept of MEMS.	(16)
	(a) (b) (a) (b) (a)	Or Derive an equation for time response of a first order system when subjected to step input. Draw the response curves and find the dynamic errors. (a) Describe the construction of different types of strain gauges and working prince. Or (b) Describe the principle of operation, construction details, characteristics applications of LVDT. (a) With neat sketch explain the working of a fiber optic displacement transducer. Or (b) Discuss the theory, working and application of Hall effect Transducer. (a) Describe the concepts and working of smart sensor with neat diagram.