٨
/ X

Reg. No.:					

Question Paper Code: 57502

B.E. / B.Tech. DEGREE EXAMINATION, APRIL 2019

Seventh Semester

Electronics and Instrumentation Engineering

15HEI702 DI C and SCADA

		15UE1/02 -	-PLC and SCADA		
		(Regu	ulation 2015)		
Duration: Three hours			Maxim	num: 100 Marks	
		Answer	ALL Questions		
		PART A - ($10 \times 1 = 10 \text{ Marks}$		
1.	Jury's Stability Test is used to analyze				
	(a) Stability of	the system	(b) Controllability of	the system	
	(c) rank of the	system	(d) none of the above	•	
2.	Velocity form of digital controllers causes Controller drift when control action is absent				
	(a) P	(b) I	(c) PI	(d) D	
3.	Small PLCs ha	ve a memory from	to store the user's logic pro	grams. CO2-R	
	(a) 2Kb to 10 H	КВ	(b) 10 Kb to 20KB		
	(c) 30Kb-40Kb)	(d) 1Gb		
4.	In a current sin	king DC input module	·	CO2-R	
	(a) The current	flows out of the input field	d device		
	(b) Requires th	at a AC sources be used w	ith mechanical switches		
	(c) The current	flows out of the input mod	dule		
	(d) Currents ca	n flow in either direction a	at the input module		
5.	Which one of t	he following is a Program	control instruction	CO3- R	
	(a) MCR	(b) Timer	(c) Coil.	(d) ALU	

6.		instruction is used as a program con	trol function.		CO3- R		
	(a) MCR	(b) RESET	(c) TIMER	(d) CNT	L		
7.	HMI mean	as Machine Interface			CO4 -R		
	(a) Human	(b)Heart	(c) Head	(d)High			
8.	To identif preferable.	y non-metal objects in a conveyor	sensor is mos	t	CO4 -R		
	(a) Capacit	tive Proximity	(b) Inductive Proximity				
	(c) IR		(d) Ultrasonic				
9.	Line Modems used to connect RTU to a network uses technique to establish communication.						
	(a) Phase S	Shift Keying	(b) Time Shift Keying				
	(c) Freque	ncy Shift Keying	(d) Coded Shift Keyin	g			
10.		is needed to provide an interface between the sensor and the SCADA network.					
	(a) Remote	e Terminal Unit	(b) DCS				
	(c) Multipl	lexer.	(d) Decoder				
		$PART - B (5 \times 2 =$	10Marks)				
11.	Determine	the Z-transform for e^{-at}			CO1 -R		
12.	. Differentiate modular PLC and fixed PLC.				CO2-U		
13.	. Write the difference between SKIP and JUMP Instruction.						
14.	Draw a ladder diagram to implement the logic $y = a'b+ab'$.				CO4-R		
15.	Give the ac	dvantage of SCADA.			CO5-U		
		PART – C (5 x 1	6= 80Marks)				
16.	(a) Discu	uss about the position and velocity form Or	n of PID system	CO1-App	(16)		
	(b) With	n an example explain about Jury's stab	ility test.	CO1-App	(16)		
17.		uss in detail about the evolution or roller and its components.	f Programmable Logic	CO2 -U	(16)		
		Or					

	(b)	(i) Explain the various timer logics in PLC.	CO2 -U	(10)
		(ii) Develop a ladder program to control traffic light in one direction.	CO2-Ana	(6)
18.	(a)	Explain in Detail about Sequencer Instruction in PLC. Draw a Ladder Logic to implement the Traffic Lights control system using sequencer instruction. Or	CO3 -U	(16)
	(b)	(i) List the various compare instructions in PLC and discuss any 3 compare instructions in detail.	CO3 -U	(10)
		(ii) Develop a ON/OFF control based ladder logic program to maintain the temperature of a tank within 1% deviation between setpoint.	CO3-Ana	(6)
19.	(a)	Explain about case study of bottle filling system with suitable diagram.	CO4-U	(16)
	(1 -)	Or With switchle discusses explain the construction and expertion of	CO4 A ===	(16)
	(b)	With suitable diagram explain the construction and operation of LPG filling system and also write a PLC program to monitor and control the reactor.	CO4 -App	(16)
20.	(a)	With a neat architecture diagram describe about SCADA Or	CO5- U	(16)
	(b)	Explain with block diagram the multiplexed ADC and DAC used in Data Acquisition System.	CO5-U	(16)