Reg. No.:					

Question Paper Code: 45504

B.E. / B.Tech. DEGREE EXAMINATION, APRIL 2019

Fifth Semester

Electronics and Instrumentation Engineering

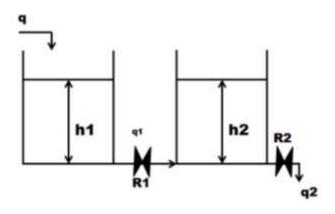
14UEI504 - PROCESS CONTROL INSTRUMENTATION

(Regulation 2014)

	(Re	gulation 2014)				
Dι	uration: Three hours		Maximum: 100 Marks			
	Answe	r ALL Questions				
	PART A	(10 x 1 = 10 Marks)				
1.	Degrees of freedom of a boat are					
	(a) 1 (b) 2	(c) 3	(d) 4			
2.	U – Tube Manometer is an example	of				
	(a) inherently second order syste(c) interacting system	` '	(b) two first order systems in series(d) non-interacting system			
3.	Most commonly used controller for c	ontrolling the temperatur	re is a controller.			
	(a) P (b) PI	(c) PD	(d) PID			
4.	The PI controller can be used in control.					
	(a) flow (b) temperate	ure (c) liquid level	(d) multi-capacity process			
5.	IAE means					
	(a) inverse arithmetic error	(b) integral	(b) integral absolute error			
	(c) internal absolute error	(d) none of	(d) none of these			
6.	Which one is the tuning method for o	esign of PID controller?				
	(a) damped oscillation method	(b) Ziegler I	Nichols method			
	(c) ultimate cycle method	(d) all of the	(d) all of the above			

7.	In boiler drum, swell effect occurs d	ue to				
	(a) sudden load (steam demand)(b) sudden load (steam demand)(c) feed water pressure variation(d) level variations	decrease				
8.	Three element control means					
	(a) feedback	(b) feedback + feedforward				
	(c) cascade	(d) feedforward+cascade				
99.	The configuration involving a single loop.	ves one measurement and one manipulated va	ariable			
	(a) cascade control	(b) feed forward control				
	(c) feedback control	(d) split range control				
10.	The can be used to control an unmeasured process output in the presence of unmeasured disturbances.					
	(a) cascade control	(b) ratio Control				
	(c) ratio split range control	(d) inferential control				
	PART -	B $(5 \times 2 = 10 \text{ Marks})$				
11.	Differentiate between servo and regu	ulator operation.				
12.	Define integral windup.					
13.	Classify the types of control valve?					
14.	An equal percentage has a maximum the full travel is 3 cm, calculate the	n flow of 50 m ³ /s and a minimum flow of 2m flow at a 1 cm opening.	³ /s. If			
15.	Identify the difference between feed	-back control and feed forward control?				
	PART - 0	$C (5 \times 16 = 80 \text{ Marks})$				
16.	(a) (i) Develop the transfer function	on of first order level process.	(8)			
	(ii) Develop the mathematical n	nodel of first order stirred tank heater.	(8)			
		Or				

- (b) (i) Illustrate servo and regulatory operation with an example for each. (8)
 - (ii) Consider the system shown in figure. Develop a mathematical model for the system. Assume that the effluent stream from a tank is proportional to the hydrostatic liquid pressure that causes the flow of liquid. Cross-sectional area of tank 1 is A1 (ft^2) and of tank 2 is A2 (ft^2). The flow rates q, q_1 , q_2 are in ft^2/min . Take necessary assumptions.



17. (a) Describe the characteristics of ON-OFF and single speed floating controllers. Also explain how they can be implemented using electronic elements. (16)

Or

- (b) Explain the operation of electronic PI and PID controller with suitable circuit diagram. (16)
- 18. (a) (i) Conclude the operation of Cohen and Coon method with the help of opened control loop. (8)
 - (ii) Explain the process reaction curve method of controller tuning. (8)

Or

- (b) (i) Explain the controller settings using Ziegler-Nichols continuous cycling method. (8)
 - (ii) In the application of the Ziegler Nichols method, a process begins oscillation with a 30% proportional band in an 11.5 min period. Examine (a) The nominal three mode controller settings and (b) Settings to give quarter amplitude response.

19.	(a)	(i)	Describe the function of an actuator. List the different types of actuators.	(8)
		(ii)	Explain the working principle of pneumatic spring actuator with valve pos	sitioner
			with a help of neat sketch. Mention the drawback of control valve v	without
			positioner.	(8)

Or

- (b) (i) Explain the working of a simple current to pressure converter with neat diagram. (8)
 - (ii) Explain the working principle of pneumatic actuated control valve with positioner with the help of neat diagram. (8)
- 20. (a) Discuss the significance of three element control strategy in boiler drum level and illustrate how it can eliminate the Shrink/ Swell and feed water pressure variation effects. Explain with a help of neat P and I Diagram. (16)

Or

(b) With suitable example explain the concept of ratio and split-range control. (16)